

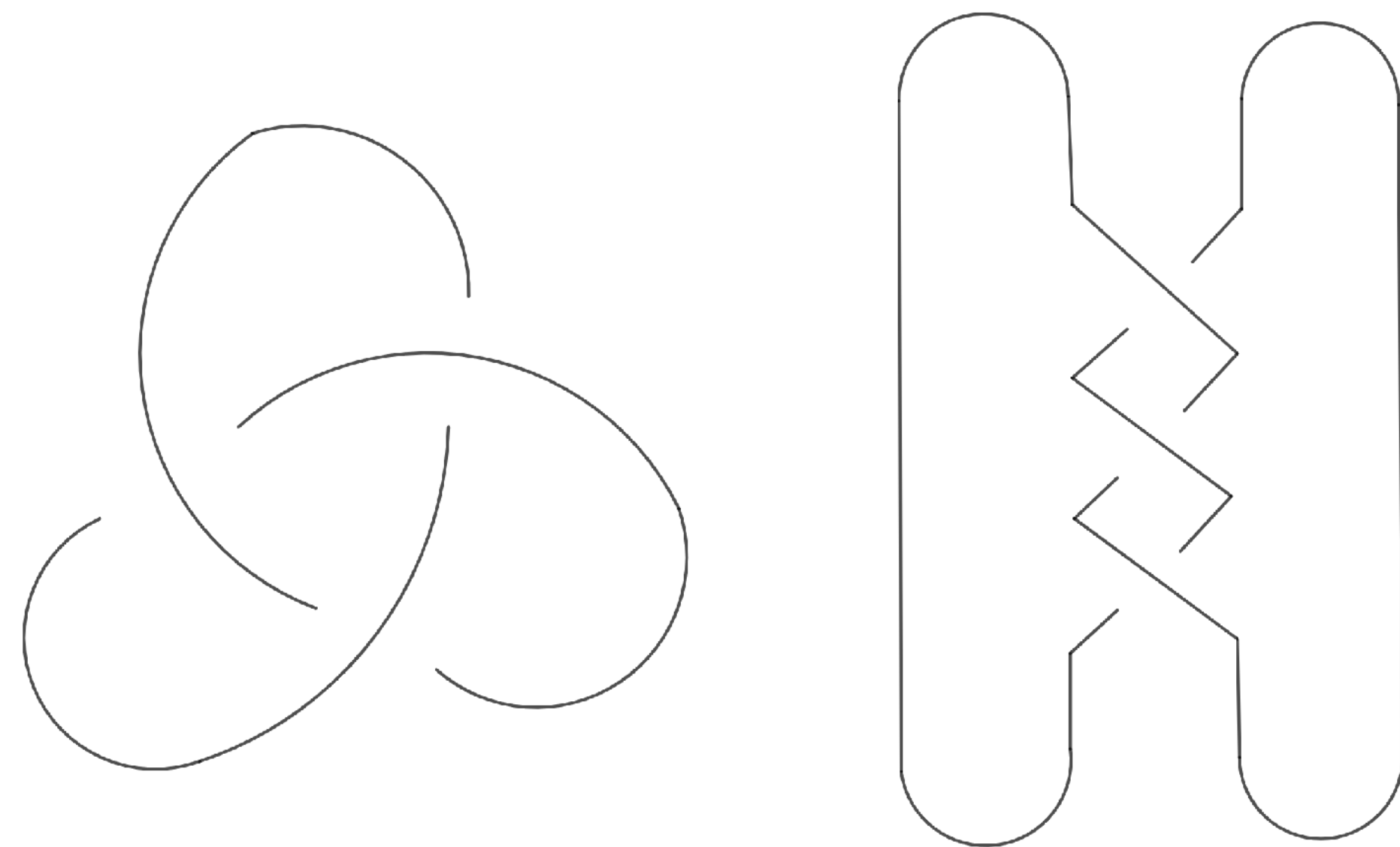
Constrained knots in lens spaces

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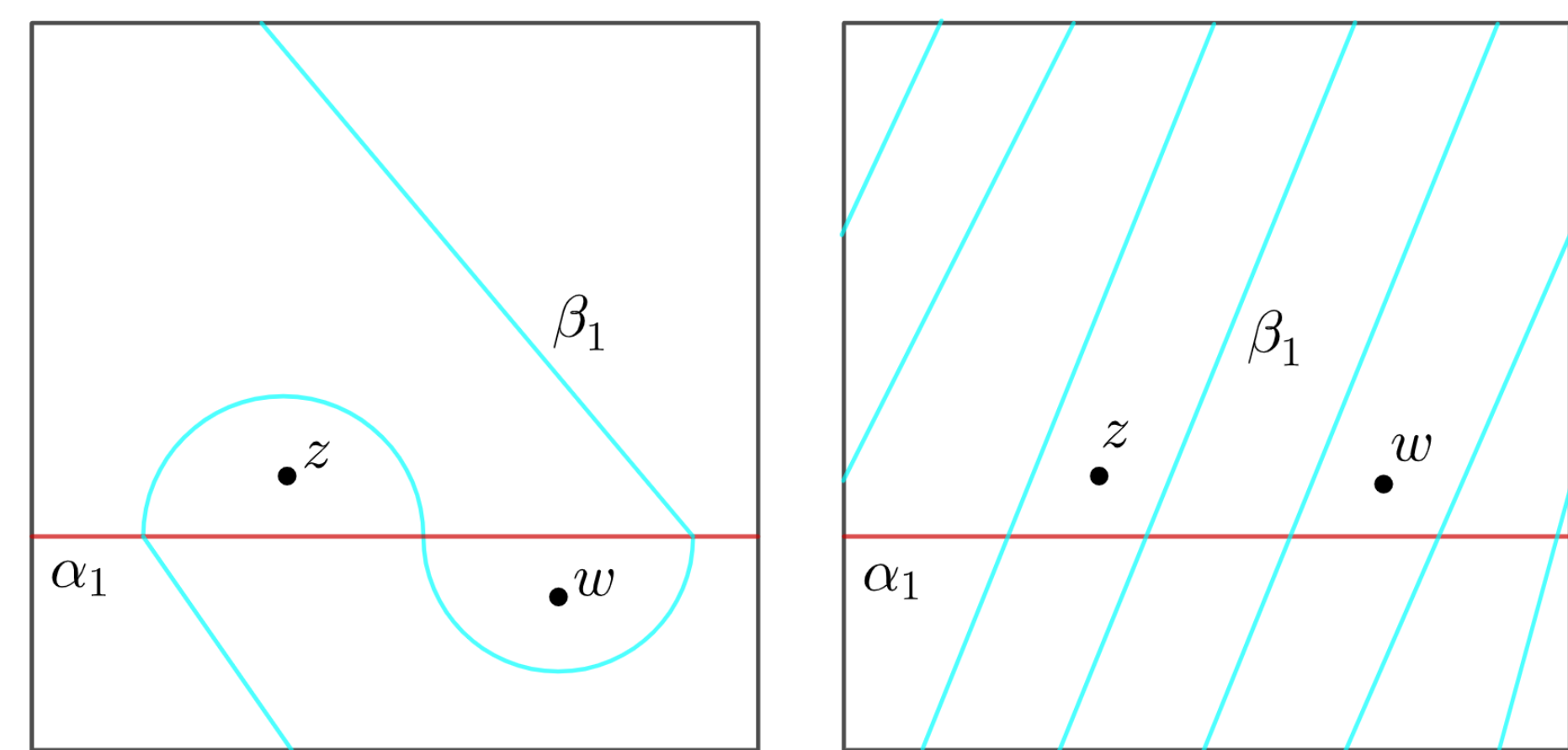
Motivation

- Constrained knots are generalizations of 2-bridge knots in S^3 and simple knots in lens spaces (see the following examples).
- Kronheimer and Mrowka conjectured that for any knot K in any closed 3-manifold, the knot Floer homology $\widehat{HFK}(Y, K)$ with \mathbb{C} coefficient is isomorphic to the instanton knot homology $KHI(Y, K)$. It is known that this conjecture holds for all alternating knots, which include all 2-bridge knots.

Examples



The left-handed trefoil knot is the 2-bridge knot $\mathfrak{b}(3, 1)$.

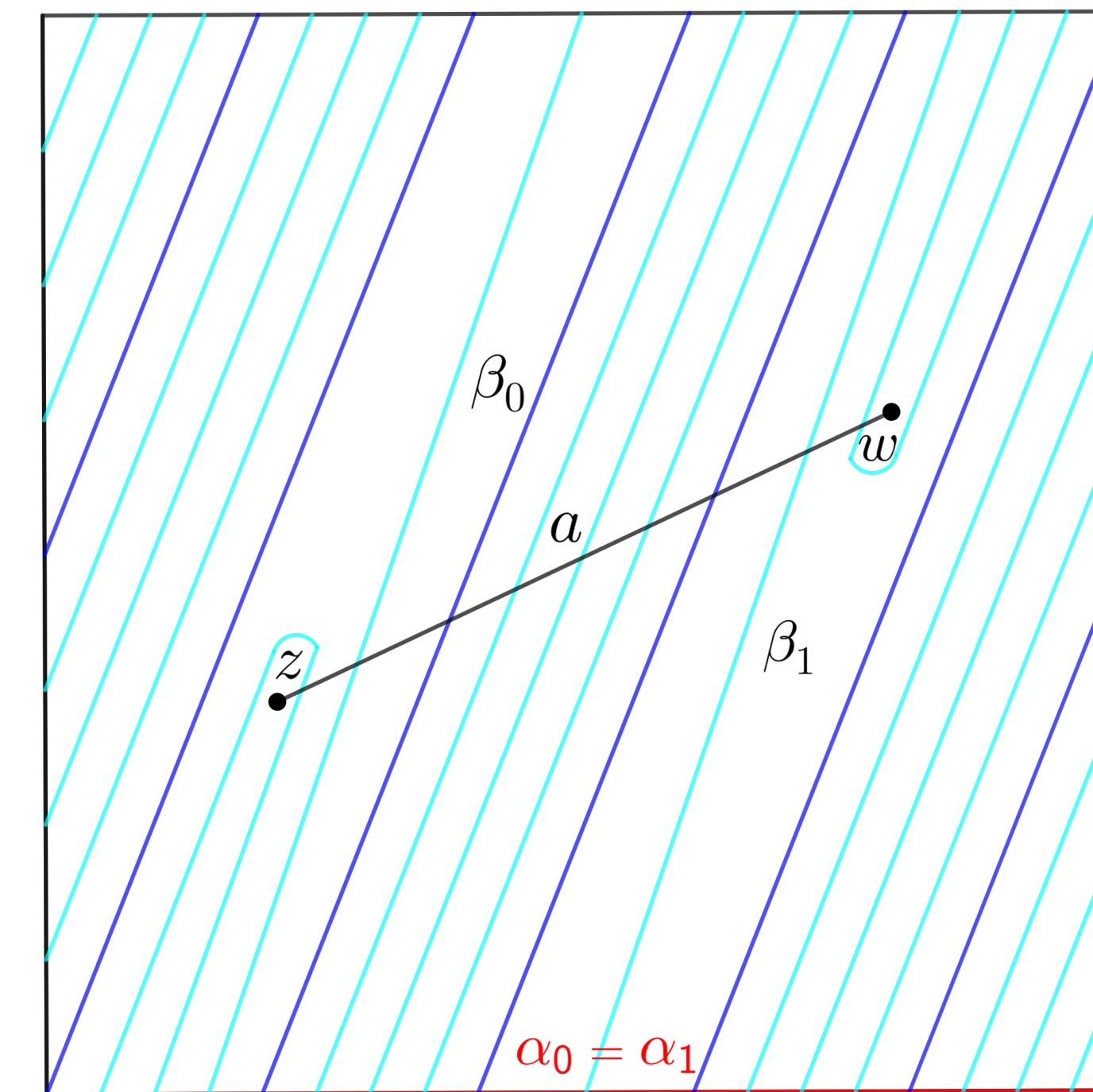


Left: a doubly-pointed Heegaard diagram of the trefoil knot. By parameterization, it is $C(1, 0, 1, 3, 1)$.

Right: a doubly-pointed Heegaard diagram of a simple knot in the lens space $L(5, 2)$. By parameterization, it is $C(5, 3, 2, 1, 0)$. Note that $L(5, 2) \cong L(5, 3)$.

Construction of a constrained knot

The right figure is a doubly-pointed Heegaard diagram $(T^2, \alpha_1, \beta_1, z, w)$ of a constrained knot K in the lens space $L(5, 2)$. The Heegaard diagram (T^2, α_0, β_0) illustrates a standard Heegaard splitting of the lens space $L(5, 2)$. The curve α_1 is the same as α_0 and the curve β_1 is chosen to be disjoint from β_0 . Two basepoints z and w indicate how to construct the knot $K = a \cup b$: choose an arc a (resp. b) in $T^2 \setminus \alpha_1$ (resp. $T^2 \setminus \beta_1$) connecting z to w and push it in the handlebody corresponding to α_1 (resp. β_1).

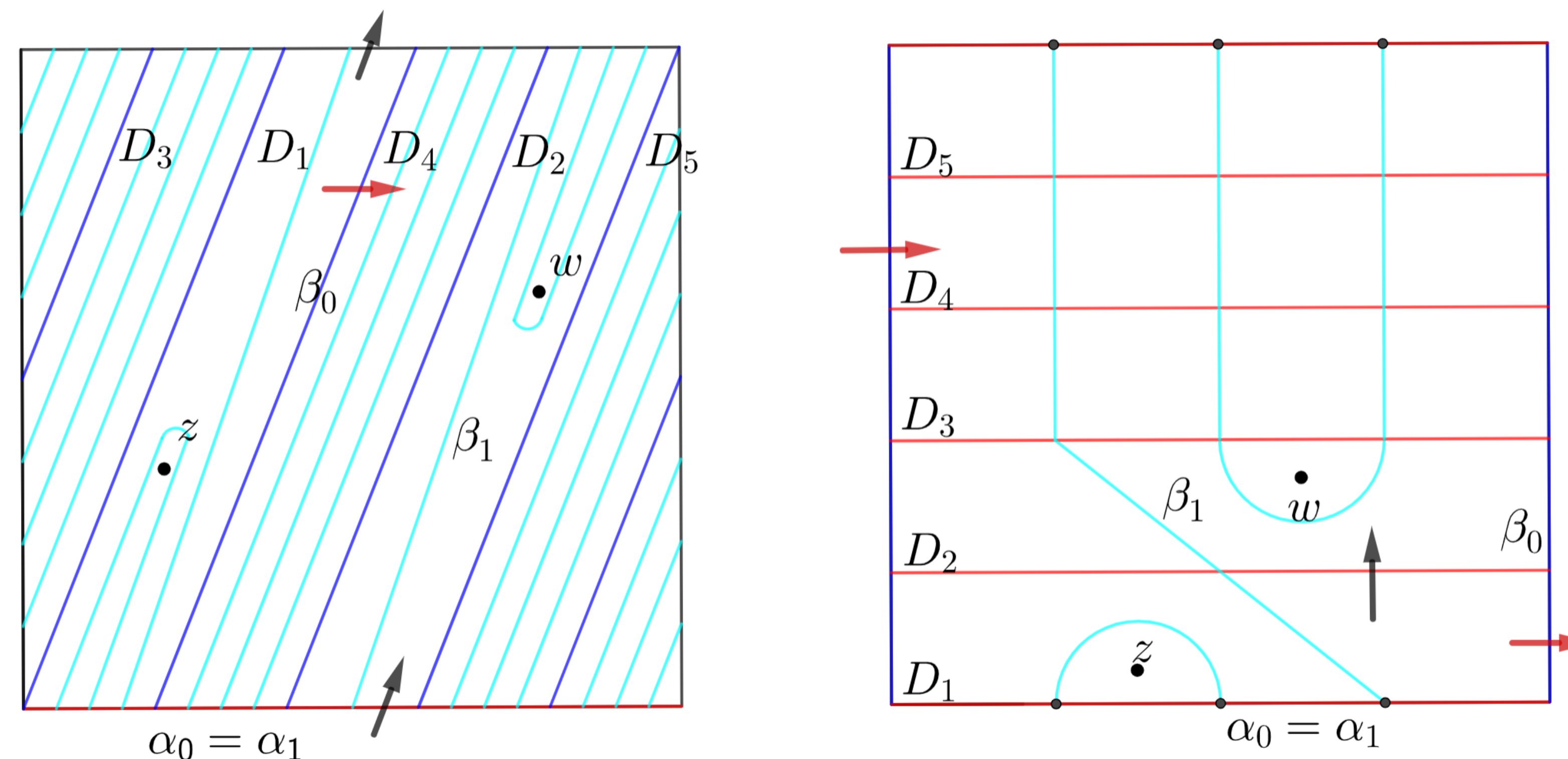


Main results

- [Ye20] There is a complete classification of constrained knots for the following parameterization.
- [LY20, BLY20, LY21] For a constrained knot K , its knot Floer homology $\widehat{HFK}(K)$ is isomorphic to its instanton knot homology $KHI(K)$, which are both determined by the Turaev torsion of K . The isomorphism $\widehat{HFK}(K) \cong KHI(K)$ can be generalized to torus knots in S^3 and lens spaces, and $(\pm 2, p, q)$ pretzel knots for odd integers p and q .

Parameterization: $C(p, q, l, u, v)$

Cut the diagram along β_0 and glue along α_0 :



$p = 5$ = the number of domains D_i ;

$q = 3$: the right-hand-side of D_1 is glued to the left-hand-side of D_{1+q} ;

$l = 2$: suppose $z \in D_1$; then $w \in D_l$;

$u = 3$ = the number of intersection points of β_1 and the subarc of α_1 ;

$v = 1$ = the number of rainbows around z .

Relation to orientable 1-cusped hyperbolic manifolds

Snappy program provides a list of 59068 orientable 1-cusped hyperbolic manifolds with at most 9 ideal tetrahedra. It can be verified that 21922 manifolds are complements of constrained knots, which, in particular, include the manifolds before $m130$. The full list can be found at <http://faniel.wiki/about/>. Note that the gap in the list (*e.g.* $m005$) is not orientable or not 1-cusped.

Name	Filling Slope & $C(p, q, l, u, v)$
$m003$	$(1, 0) \& (10, 3, 3, 1, 0), (-1, 1) \& (5, 4, 5, 3, 1)$
$m004$	$(1, 0) \& (5, 4, 5, 3, 1)$
$m006$	$(1, 0) \& (1, 0, 1, 5, 2)$
$m007$	$(0, 1) \& (15, 4, 2, 1, 0), (1, 0) \& (5, 3, 4, 3, 1)$
$m009$	$(1, 0) \& (3, 1, 2, 3, 1)$
$m010$	$(1, 0) \& (2, 1, 2, 5, 2)$
$m011$	$(1, 0) \& (6, 5, 6, 3, 1)$
$m015$	$(1, 0) \& (13, 3, 3, 1, 0), (0, 1) \& (9, 4, 9, 3, 1)$
$m015$	$(1, 0) \& (1, 0, 1, 7, 2)$
...	...
$m130$	$(1, 0) \& (16, 3, 6, 1, 0), (0, 1) \& (16, 7, 16, 3, 1)$
$m135$	Not from any constrained knot
...	...

References

- [BLY20] John A. Baldwin, Zhenkun Li, and Fan Ye. Sutured instanton homology and Heegaard diagrams. *ArXiv: 2011.09424, v1*, 2020.
- [LY20] Zhenkun Li and Fan Ye. Instanton Floer homology, sutures, and Heegaard diagrams. *ArXiv: 2010.07836, v2*, 2020.
- [LY21] Zhenkun Li and Fan Ye. Instanton Floer homology, sutures, and Euler characteristics. *ArXiv: 2011.09424, v1*, 2021.
- [Ye20] Fan Ye. Constrained knots in lens spaces. *ArXiv:2007.04237, v1*, 2020.